

Remote Monitoring System + Anti Collision

www.innoval.biz



ABOUT US

Innoval was born from

30 years of experience of its technical and operational team in electronic Systems for industrial mobile vehicles.

We design all our products by ourselves, *hardware* and *software*, for this reason our strong points are the customization and flexibility.

30+
years of experience

5000 systems

80 customers

11 countries



OEM

We supply our systems to CAN-bus communication, CANopen, J1939, FMS protocols.





REVAMPING

To ensure that the vehicles are efficient and functional even after several years, we carry out a complete electronic revamping of port mobile cranes and stackers of different brands.





"Internet of Machines is a next generation machine telemetry and fleet remote monitoring System that can satisfy customer needs"



Industries



What do customers want?

Know if the machine is working

Know if the machine is operating correctly

Know the position of the machine

Inspect malfunctions easily and rapidly

Plan machine maintenance in advance

Quickly monitor all vehicles

What do INNOVAL provide?

Faster response to machine problems

Historical data for machine efficiency analysis

Machine fault predictions

Control unit with GPS/LTE on the machine

Real time alerts and warnings

24/7 monitoring

A single interface to remote monitor all vehicle











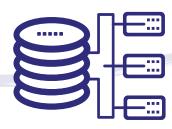
Innoval System includes:

CONTROL UNIT

DATA COLLECTOR

DASHBOARD







V2 control unit in the machine and a VGA display (optional)

DC runs **On Premise** or on **AWS Cloud**

Records machine data in a database allowing big data elaborations such as KPI (Key Performance Indicator) computation and long term analysis Interactive

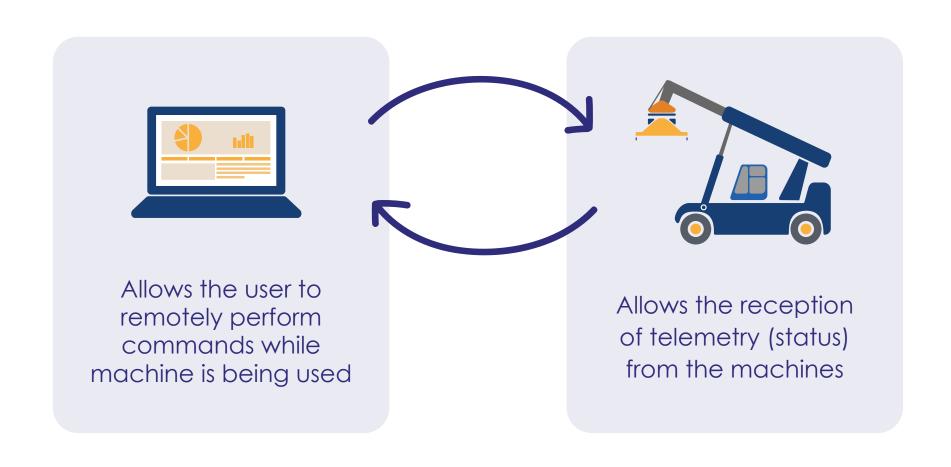
dashboard for end

user to view the

interest data



"Two ways" communication System:



What WE MANAGE



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User authentication by NFC badge

Management of operator list enabled to the utilization

Checklist for the vehicle start

Operator detection (sensor located on the driver seat)



Recording and sending images in case of bumps

Inhibition to start the machine from remote

Recording of all faults, alarm, system by-pass

Pre alarms and alarms based on abnormal conditions

Spreader Status (TL seated, TL locked, TL unlocked)

Tires pressure and temperature monitoring TPMS

Stability Reserve Status



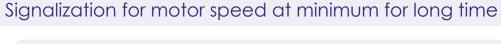


Real time position of the machine via GPS tracking

Acceleration/Speed reduction based on areas

Trace route of veichles

Geofencing



Date and Time of container handling start and ending

Travelled Distance of the machine during the handling

Container pick up and release height

Container Heandling time duration

Handled Container Size and Weight

Burnt fuel during the handling

Boom Angle and Extension

Lifting Height of Spreder

Actual Load Lifted







Engine Oil Pressure and Temperature

Engine Coolant Temperature

Hydraulic Lift Cylinders Pressure

Engine Fuel Level

Engine Torque

Engine Rpm

REMOTE



Real Time graphic monitoring of parameters and recording

Data encryption and compression before being sent to Server

Remote file updating

Remote software updating

Multi language software

VNC Virtual Network Computing

Hardware on board

DCU-C V2

Master Control Unit



DESCRIPTION:

The DCU-C V2 is a fully programmable automotive grade controller designed to be used as high performance master controller and Man-Machine-Interface (combined with an external VGA display) in industrial vehicles.

FEATURES:

CPU master: NXP i.MX6DL (2 x Cortex-A9 @ 800Mhz), Internal memory:

144 kByte RAM (OCRAM), 32i + 32d kByte L1 Cache, 512 kByte L2 Cache

CPU slave (supervisor): NXP LPX5526 150 MHz (Cortex-M33), Memory: 256 kByte Flash, 144 kByte RAM

3 axis accelerometer, 3 axis gyroscope

3 axis magnetic-sensor (optional)

miniPCle slot for LTE/4G with micro SIM-Holder M.2 slot

GPS module

Dashboard

Customer may develop its own dashboard by accessing the saved machine data or INNOVAL can supply its own dashboard



WEB PORTAL BASED

(rest API based)



CUSTOMIZABLE

layout



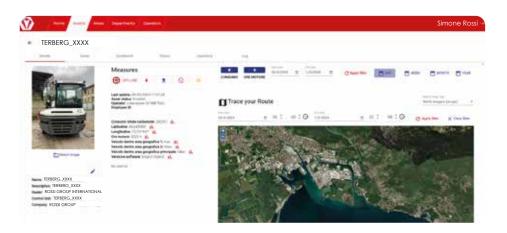
CONFIGURABLE

machine report measures



MULTI

user/customer/dealer





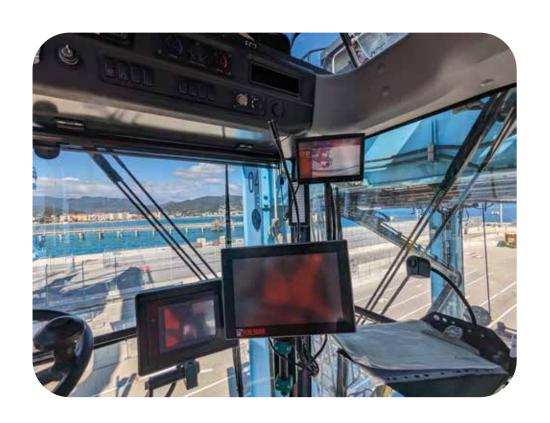


ANTI-COLLISION SYSTEM

The Anti-Collision
system can be
"standalone" or
integrated in our
Remote Monitoring
System



Ultra wide band (UWB) based Anti-collision system for Harbor Vehicles



The system is based on 4 UWB transceivers mounted on the 4 extremities of the Vehicle, for example on a Straddle Carrier on the 4 legs or on the Bumpers. Mounted like this the system will measure the distance to any equipped service Vehicle or person in a range of up to 20 meters around the Vehicle.

PRE-ALARM & ALARM

The Client can define two different distances one for a pre-alarm and one as alarm, this gives the possibility to inform the Operator on the vehicle early enough to react on the alarm, but will prevent false alarms.

In opposite to camera based systems the UWB system can (with some limitations) see "around corners" and warn the Operator about a Service Vehicle or a Person out of sight.



Further the system generates virtually non falls alarms as it depends on a transceiver on the Service Vehicle or the Person (TAG).

The user can exclude the detection of certain types of Vehicles, for example to prevent constant alarms if a group of Vehicles works in close proximity, but remains active for other types of Vehicles and Persons.



RED ZONE System

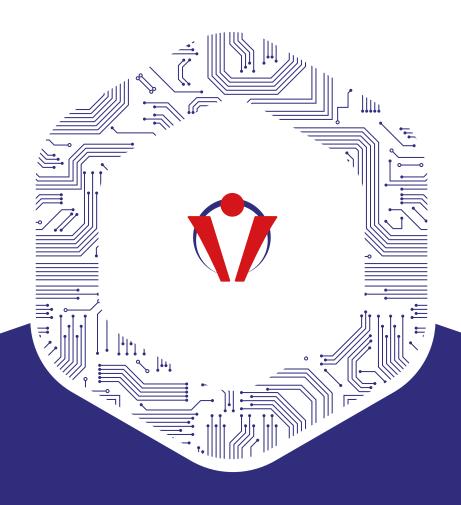
In some Harbor areas any entering Service Vehicle has to be recognized, and all Shuttles (Straddle Carriers or Reach Stackers) have to stay still, until the Service Vehicle leave the working area.

This is normally archived by radio communication between the Supervisor and the Operators on the Machines, but this can lead to misunderstanding (the operator did not hear the communication for some reasons).

To "automate" the transmission of the command our Remote Monitoring system can be enhanced by a system that gives the Supervisor the possibility to block certain Geographic areas (Zones) via a hand held Computer (or tablet).

INNOVAL System can:

- Show the position of all Vehicles in the Area in real-time
- Block a Zone by simply touching the zone on the Tablet (the Operator has a visual and auditive warning in the cabin)
- Verifying that the command was received by all Vehicles in real-time
- Release the blocked Zone
- The system can handle multiple zones and multiple Supervisors / Tablets.



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